# EECS 16B Designing Information Devices and Systems II

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### **Announcements**

- Midterm #1
  - Redo is due Wed 3/13 @ 11:59pm
- Lab
  - Midterm lab report due tomorrow @ 11:59pm
  - Buffer lab this week, System Identification next week
- Lots of Linear Algebra coming up
  - resource: Gil Strang lectures (YouTube playlist or MIT OCW website)

## Today

- Review
  - discrete time and "discretizing" a system
  - least squares optimization (from 16A)
- System Identification

#### **Continuous Time**

$$\ddot{x} - 3\dot{x} + 2x = u(t)$$
 differential equation

$$x_i - 3x_{i-1} + 2x_{i-2} = u_i$$
 difference equation

#### **Continuous Time**

$$\ddot{x} - 3\dot{x} + 2x = u(t)$$
 differential equation

$$x = \sum_k c_k e^{\lambda_k t}$$
 form of homogeneous solution in CT

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 characteristic equation in CT

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 state space solution in DT

$$\vec{x}(t) = e^{At}\vec{x}(0) + \int_0^t e^{A(t-\tau)}B\vec{u}(\tau)d\tau$$
  $\vec{x}_i = A^i\vec{x}_0 + \sum_{k=0}^{i-1} A^{i-1-k}B\vec{u}_k$ 

## "Discretization" of a System

Given a diagonalizable CT system specified by:

$$A_c = V\Lambda V^{-1}$$
  $B_c$ 

and a timestep  $\Delta$ , the DT equivalent system is given by:

$$A_d = V e^{\Lambda \Delta} V^{-1}$$
  

$$B_d = V (e^{\Lambda \Delta} - I_n) \Lambda^{-1} V^{-1} B_c$$

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