

**EECS 16B**

# **Designing Information Devices and Systems II**

## **Lecture 5**

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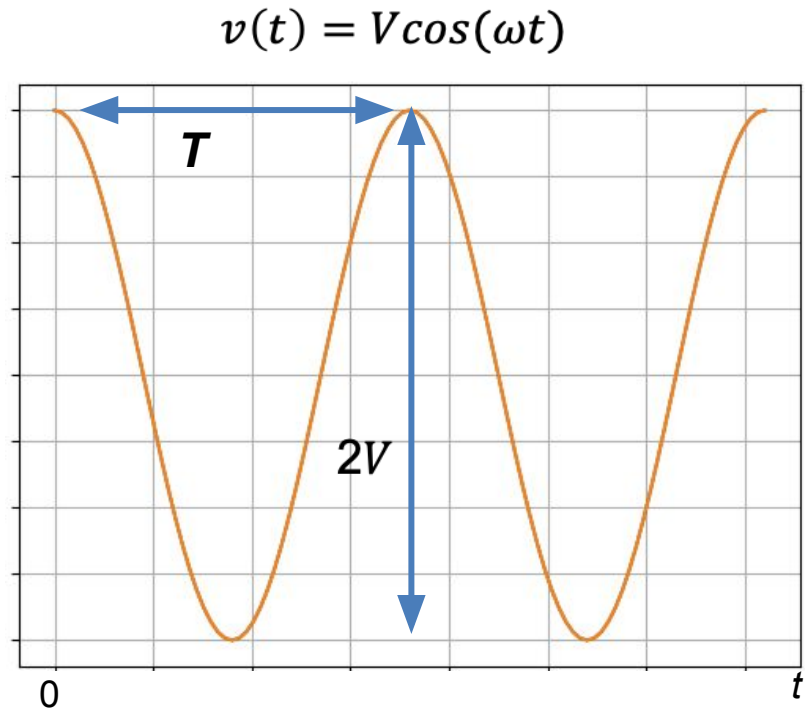
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# Transient Response

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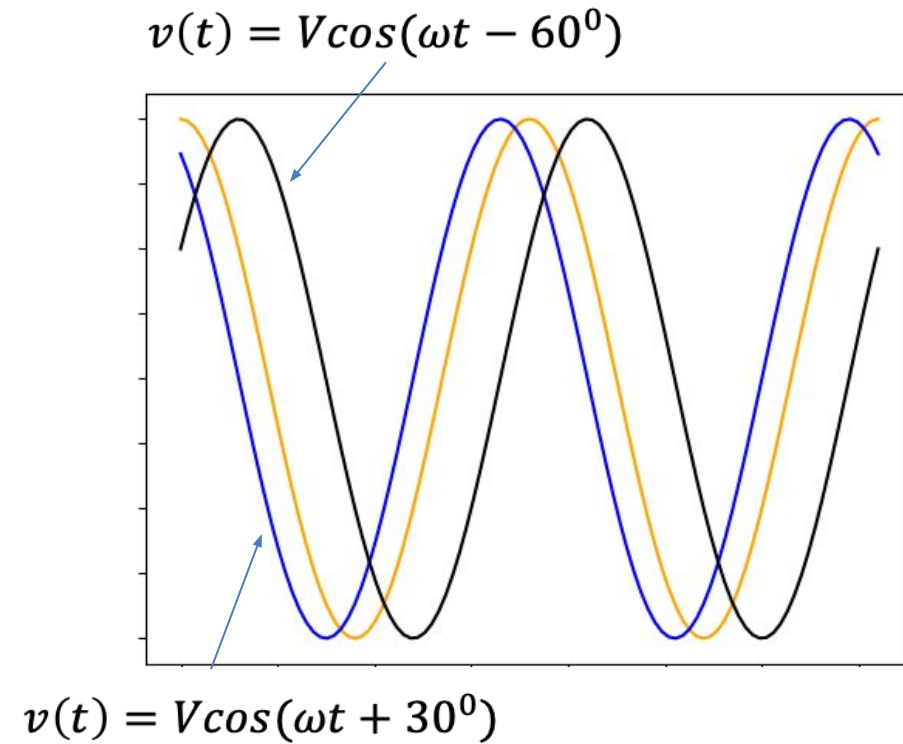
- Outline
  - Phasors
  - Complex Impedances
  - Solution of circuits using complex impedances
- Reading- Hambley text sections 5.2, 5.3, 5.4, 5.6, 5.5, slides

# Recap: Sinusoidal voltages



$T$ : Period

$$\omega = \frac{2\pi}{T}$$



# Recap: How do we add arbitrary sinusoids?

$$v(t) = 10\cos\omega t + 5\sin\omega t - 5\cos(\omega t - 30^\circ)$$

$$v(t) = 10\cos\omega t + 5\cos(\omega t - 90^\circ) - 5\cos(\omega t - 30^\circ)$$

Remember?  $\cos(a + b) = \cos a \cos b - \sin a \sin b$

Lets do it it differently  $e^{j\theta} = \cos\theta + j\sin\theta$

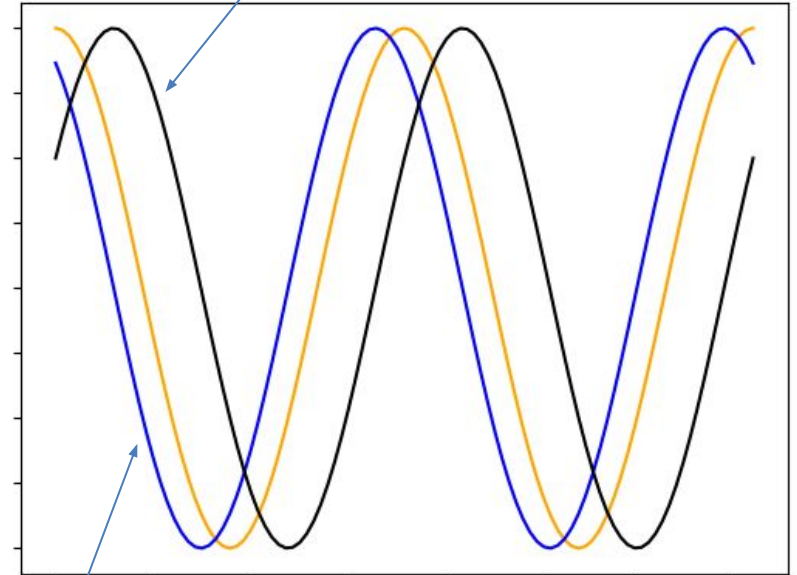
$$e^{-j\theta} = \cos\theta - j\sin\theta$$

Then

$$\cos\theta = \frac{1}{2}(e^{j\theta} + e^{-j\theta})$$

$$\sin\theta = \frac{1}{2j}(e^{j\theta} - e^{-j\theta})$$

$$v(t) = V\cos(\omega t - 60^\circ)$$



$$v(t) = V\cos(\omega t + 30^\circ)$$

# Recap: How do we add arbitrary sinusoids?

$$\begin{aligned}v(t) &= 10\cos\omega t + 5\cos(\omega t - 90^\circ) - 5\cos(\omega t - 30^\circ) \\&= \frac{1}{2}e^{j\omega t}[10] + \frac{1}{2}e^{j(\omega t - 90^\circ)}[5] - \frac{1}{2}e^{j(\omega t - 30^\circ)}[5] \\&\quad + \frac{1}{2}e^{-j\omega t}[10] + \frac{1}{2}e^{-j(\omega t - 90^\circ)}[5] - \frac{1}{2}e^{-j(\omega t - 30^\circ)} \\&= \frac{1}{2}e^{j\omega t}[10 + 5e^{-j90} - 5e^{-j30}] + \frac{1}{2}e^{-j\omega t}[10 + 5e^{+j90} - 5e^{+j30}] \\&= \frac{1}{2}e^{j\omega t}[10 + 5\cos 90 - j5\sin 90 - 5\cos 30 + j5\sin 30] + cc \\&= \frac{1}{2}e^{j\omega t}\left[10 + 0 - j5 - 5\frac{\sqrt{3}}{2} + \frac{j5}{2}\right] + cc \\&= \frac{1}{2}e^{j\omega t}[5.66 - j2.5] + cc \\&= \frac{1}{2}6.18e^{j(\omega t - 23^\circ)} + cc \\&= 6.18\cos(\omega t - 23^\circ)\end{aligned}$$

$$\begin{aligned}\cos\theta &= \frac{1}{2}(e^{j\theta} + e^{-j\theta}) \\ \sin\theta &= \frac{1}{2}(e^{j\theta} - e^{-j\theta})\end{aligned}$$

$$Ae^{-j\theta} = 5.66 - j2.5$$

$$Ae^{j\theta} = 5.66 + j2.5$$

$$A^2 = 5.66^2 - j^2 2.5^2$$

$$A^2 = 5.66^2 + 2.5^2$$

$$A = \sqrt{5.66^2 + 2.5^2} = 6.18$$

$$\cos\theta = 5.66/6.18; \sin\theta = 2.5/6.18$$

$$\tan\theta = \frac{2.5}{5.66} = 0.44$$

$$\theta = 0.41 = 23^\circ$$

# Recap: Some Observations

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$$\begin{aligned}v(t) &= \frac{1}{2}e^{j\omega t}[5.66 - j2.5] + cc \\ &= \frac{1}{2}6.18e^{j(\omega t - 23^\circ)} + \frac{1}{2}6.18e^{-j(\omega t - 23^\circ)} \\ &= \frac{1}{2}6.18[\cos(\omega t - 23^\circ) + j\sin(\omega t - 23^\circ)\cos(\omega t - 23^\circ) - j\sin(\omega t - 23^\circ)] \\ &= \text{Real} [6.18e^{j(\omega t - 23^\circ)}]\end{aligned}$$

Phasors



In short hand, it is represented as  $6.18 \angle -23^\circ$

# Some Observations

$$A(t) = 5\cos(\omega t) = \text{Real}[5e^{j(\omega t)}]$$

$$B(t) = 5\cos(\omega t - 90^\circ) = \text{Real}[5e^{j(\omega t - 90^\circ)}]$$

$$C(t) = 5\cos(\omega t + 90^\circ) = \text{Real}[5e^{j(\omega t + 90^\circ)}]$$

At any given time  $t$ ,  $B(t)$  is trailing or lagging behind  $A(t)$  by  $90^\circ$  while  $C(t)$  is leading  $A(t)$  by the same amount

Let us now look at the phasors at  $t=0$

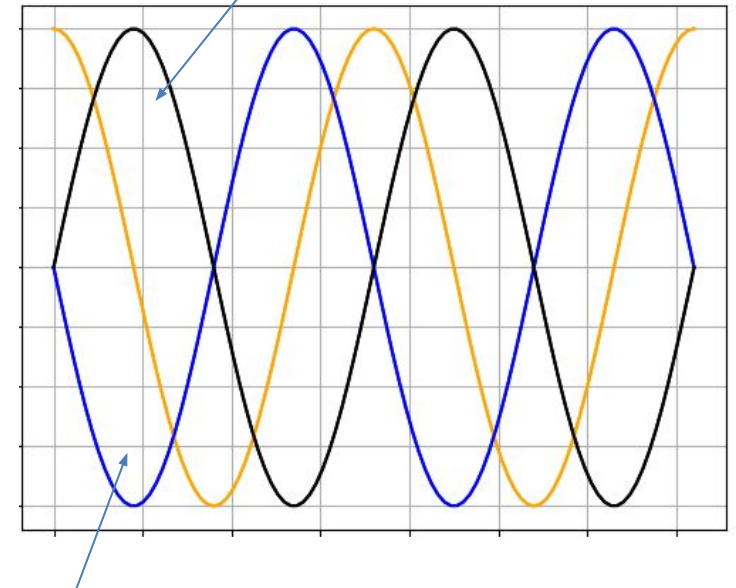
$$5e^{j(\omega t - 90^\circ)} = 5$$

$$5e^{j(\omega t - 90^\circ)} = 5(\cos 90^\circ - j\sin 90^\circ) = -j5$$

$$5e^{j(\omega t + 90^\circ)} = 5(\cos 90^\circ + j\sin 90^\circ) = +j5$$

Therefore  $+j$  or  $-j$  signifies signals having  $90^\circ$  phase lead or lag respectively.

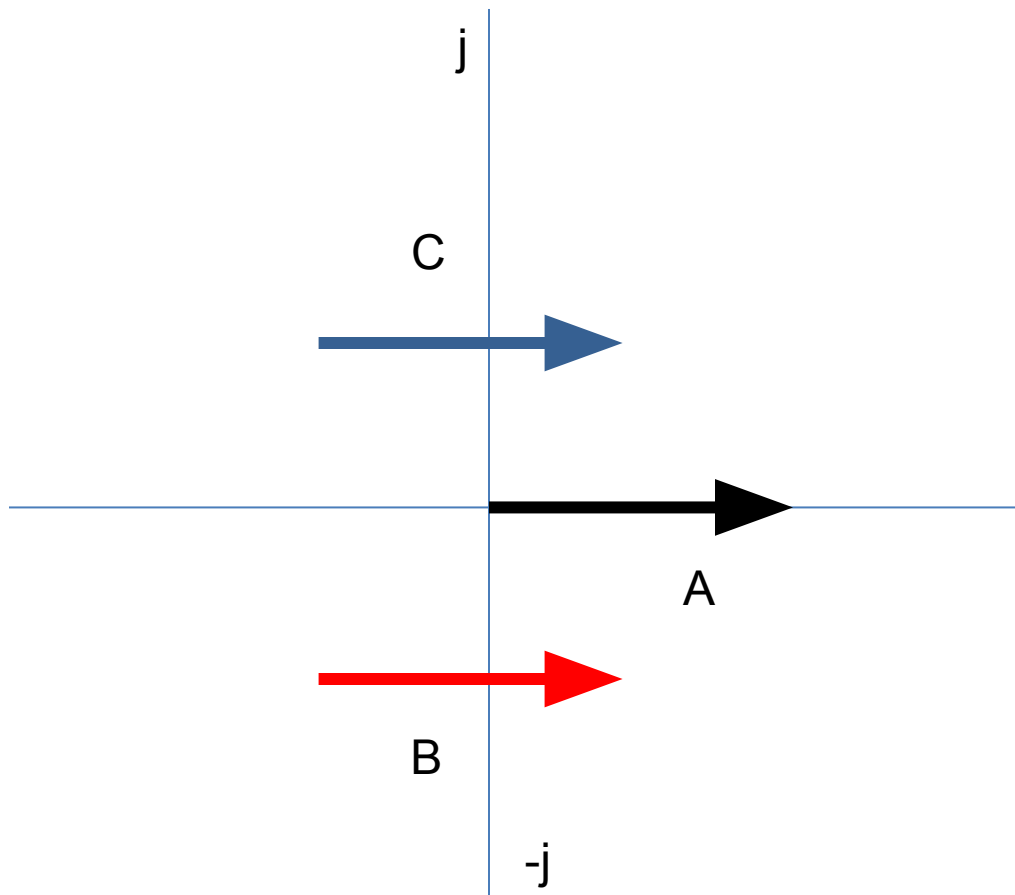
$$v(t) = V\cos(\omega t - 90^\circ)$$



$$v(t) = V\cos(\omega t + 90^\circ)$$

# Some Observations

$+j$  or  $-j$  signifies signals having  $90^\circ$  phase lead or lag respectively.



$$5e^{j(\omega t - 90^\circ)} = 5$$

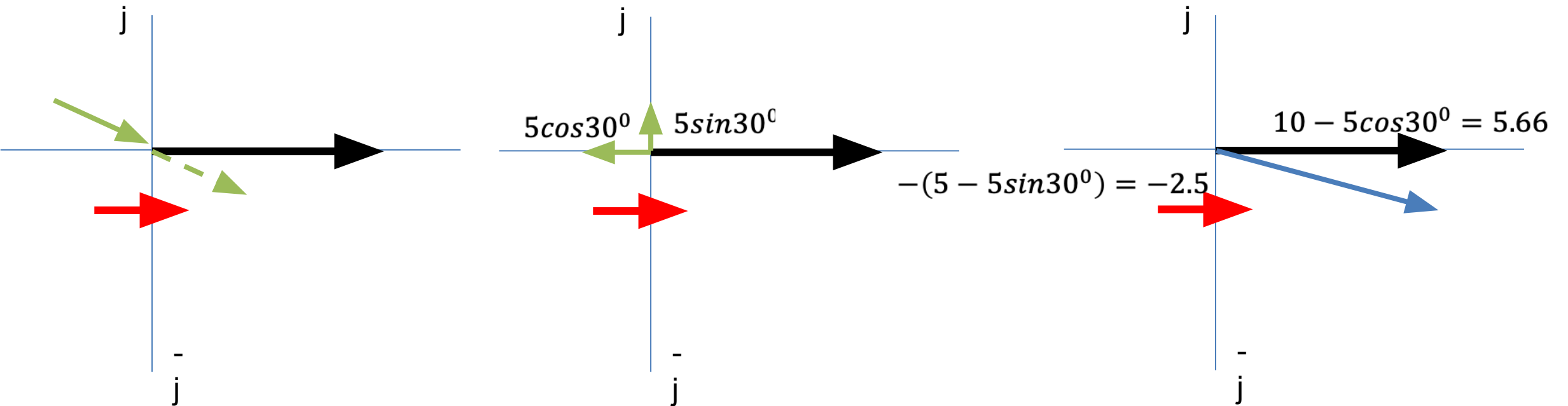
$$5e^{j(\omega t - 90^\circ)} = 5(\cos 90^\circ - j\sin 90^\circ) = -j5$$

$$5e^{j(\omega t + 90^\circ)} = 5(\cos 90^\circ + j\sin 90^\circ) = +j5$$



# Some Observations

$$\begin{aligned}
 v(t) &= 10\cos\omega t + 5\cos(\omega t - 90^\circ) - 5\cos(\omega t - 30^\circ) \\
 &= 10 + 5\angle -90^\circ - 5\angle -30^\circ \quad \text{In phasor notation} \\
 &= 6.18\angle -23^\circ
 \end{aligned}$$



Phasors are like vectors where the phase angle denotes the angle between coordinate axes with  $j$  representing  $90^\circ$

# Some Observations

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What is  $\frac{1}{\angle\theta}$ ?

# Complex Impedances

## Inductance:

Say a sinusoidal current is flowing in a circuit with inductance

$$i(t) = I_0 \sin(\omega t) = I_0 \cos(\omega t - 90^\circ)$$

$$v_L(t) = L \frac{di}{dt} = \omega L I_0 \cos \omega t$$

Therefore, the current in an inductor lags the voltage by  $90^\circ$

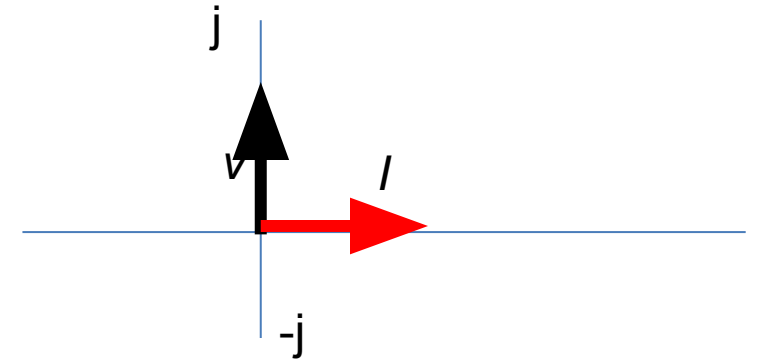
In the phasor notation

$$V = \omega L I_0$$

$$I = I_0 \angle -90^\circ$$

Then, inductive impedance

$$Z_L = \frac{V}{I} = \frac{\omega L}{\angle -90^\circ} = \frac{\omega L}{-j} = j\omega L$$



We could have obtained the same result working directly with exponentials

$$V = L \frac{d}{dt} [I_0 e^{j(\omega t - 90^\circ)}]$$

$$V = Lj\omega [I_0 e^{j(\omega t - 90^\circ)}]$$

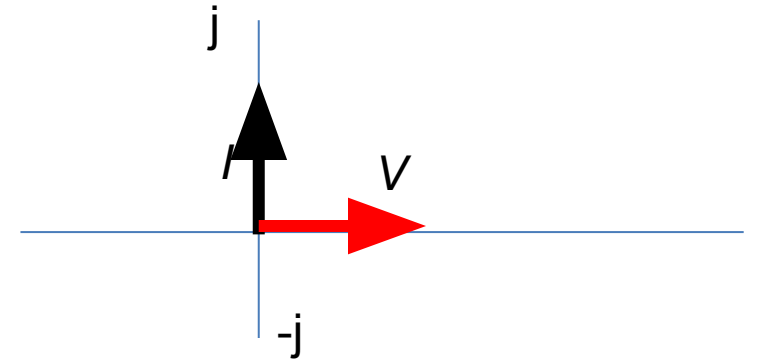
$$V = j\omega L I_0 \angle -90^\circ$$

$$V = j\omega L I$$

# Complex Impedances

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Capacitance:



# Complex Impedances

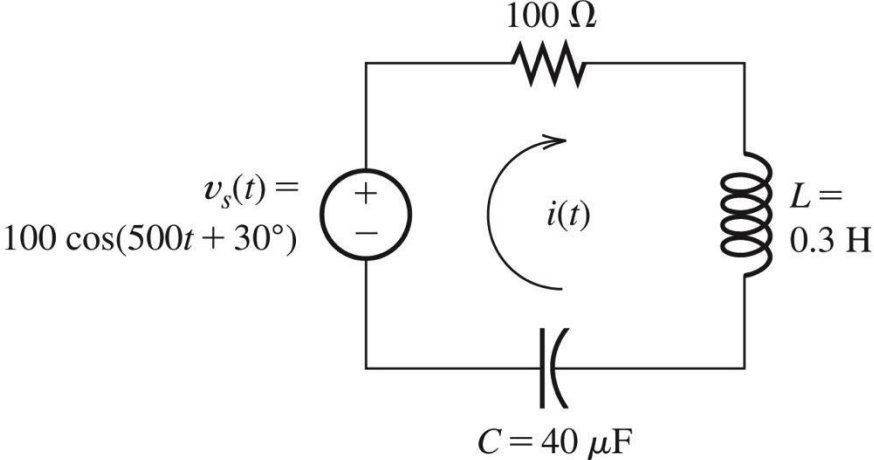
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- AC steady-state analysis using phasors allows us to express the relationship between current and voltage using a formula that looks like Ohm's law:

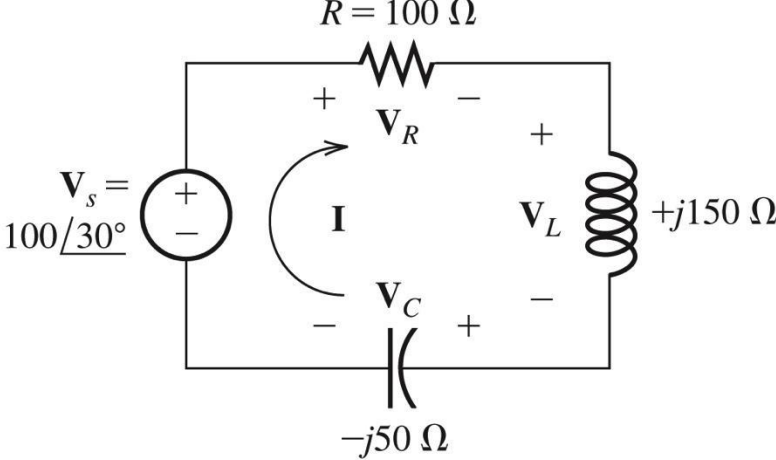
$$\mathbf{V} = \mathbf{IZ}$$

- Impedance depends on the frequency  $\omega$ .
- Impedance is a complex number.
- Impedance allows us to use the same solution techniques for AC steady state as

# Circuit Solution with sinusoidal sources



(a)



(b)

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# Circuit Solution with sinusoidal sources

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# Power in AC Circuits

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# Power in AC Circuits

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