

## Homework 11

**This homework is due on Sunday, November 13, 2022 at 11:59PM. Self-grades and HW Resubmissions are due the following Sunday, November 20, 2022 at 11:59PM.**

### 1. Spectral Theorem for Real Symmetric Matrices

We want to show that every real symmetric matrix can be diagonalized by a matrix of its orthonormal eigenvectors. In other words, a symmetric matrix  $S \in \mathbb{R}^{n \times n}$ , i.e., a matrix  $S$  such that  $S = S^\top$ , can be written as  $S = V\Lambda V^\top$ , where  $V \in \mathbb{R}^{n \times n}$  is an orthonormal matrix of eigenvectors of  $S$  and  $\Lambda \in \mathbb{R}^{n \times n}$  is a diagonal matrix of corresponding real eigenvalues of  $S$ . This is called the Spectral Theorem for real symmetric matrices.

To do this, we will use a proof which is similar to the proof of existence of the Schur decomposition. Along the way, we will practice block matrix manipulation and the induction proof technique.

- (a) One part of the spectral theorem can be proved without any further delay. **Prove that the eigenvalues  $\lambda$  of a real, symmetric matrix  $S$  are real.**

(HINT: Let  $\lambda$  be an eigenvalue of  $S$  with corresponding nonzero eigenvector  $\vec{v}$ . Evaluate  $\vec{v}^\top S \vec{v}$  in two different ways:  $\vec{v}^\top (S \vec{v})$  and  $(\vec{v}^\top S) \vec{v}$ . What does this show about  $\lambda$ ?)

**Solution:** Using the fact that  $S$  is real and symmetric so  $\bar{S} = S = S^\top$ , we get

$$\vec{v}^\top (S \vec{v}) = \vec{v}^\top (\lambda \vec{v}) = \lambda \vec{v}^\top \vec{v} = \lambda \|\vec{v}\|^2 \quad (1)$$

$$(\vec{v}^\top S) \vec{v} = (S \vec{v})^\top \vec{v} = (\bar{S} \vec{v})^\top \vec{v} = (\bar{\lambda} \vec{v})^\top \vec{v} = \bar{\lambda} (\vec{v}^\top \vec{v}) = \bar{\lambda} \|\vec{v}\|^2. \quad (2)$$

where  $\|\vec{v}\|^2 = \sum_{i=1}^n |v_i|^2$ . Since  $\vec{v} \neq \vec{0}_n$ , we know that  $\|\vec{v}\|^2 > 0$ , and so  $\lambda = \bar{\lambda}$ . Thus  $\lambda$  is real.

- (b) For the main proof that every real symmetric matrix is diagonalized by a matrix of its orthonormal real eigenvectors, we will proceed by *induction*.

Recall that an inductive proof trying to prove a statement that depends on  $n$ , say  $P_n$ <sup>1</sup>, is true for all positive integers  $n$ , has two steps:

- A base case – prove that  $P_1$  is true.
- An inductive step – for every  $n \geq 2$ , given that  $P_{n-1}$  is true, prove that  $P_n$  is true.<sup>2</sup>

By doing these two steps, we show  $P_n$  is true for all  $n$ .

In our case, the statement  $P_n$  is "every  $n \times n$  symmetric matrix  $S$  can be diagonalized as  $S = V\Lambda V^\top$ , where  $V$  is the real orthonormal matrix of eigenvectors of  $S$ , and  $\Lambda$  is the real diagonal matrix of corresponding eigenvalues of  $S$ ."

<sup>1</sup>Lecture used  $S_n$ , but  $S$  is already being used for symmetric matrix here.

<sup>2</sup>This is the so-called *weak induction* paradigm; it contrasts with *strong induction*, which you can learn in future classes like CS70.

**Show the base case: every  $1 \times 1$  symmetric matrix  $S$  can be written as  $S = V\Lambda V^\top$ , where  $V$  is a real and orthonormal matrix of eigenvectors of  $S$ , and  $\Lambda$  is a real and diagonal matrix of corresponding eigenvalues of  $S$ .**

(HINT: Every  $1 \times 1$  matrix is symmetric, and also diagonal, by definition; the only real orthonormal  $1 \times 1$  matrices are  $\begin{bmatrix} 1 \end{bmatrix}$  and  $\begin{bmatrix} -1 \end{bmatrix}$ .)

**Solution:** Let  $S = \begin{bmatrix} s \end{bmatrix}$ . Since  $\begin{bmatrix} 1 \end{bmatrix}$  is a real and orthonormal matrix, and  $\begin{bmatrix} s \end{bmatrix}$  is diagonal,  $S = \begin{bmatrix} 1 \end{bmatrix} \begin{bmatrix} s \end{bmatrix} \begin{bmatrix} 1 \end{bmatrix}^\top$  is an orthonormal diagonalization of  $S$ . Since  $S\vec{x} = s\vec{x}$  for all  $\vec{x} \in \mathbb{R}^1$ , we see that  $\begin{bmatrix} s \end{bmatrix}$  is a matrix of eigenvalues of  $S$ , and also that any vector is an eigenvector so an orthonormal matrix of eigenvectors of  $S$  is  $\begin{bmatrix} 1 \end{bmatrix}$ .

It is also possible to answer with  $S = \begin{bmatrix} -1 \end{bmatrix} \begin{bmatrix} s \end{bmatrix} \begin{bmatrix} -1 \end{bmatrix}^\top$ .

- (c) With the base case done, we are now in the inductive step. Let  $S$  be an arbitrary  $n \times n$  symmetric matrix; ultimately, we want to show that  $S = V\Lambda V^\top$ , where  $V$  is a real and orthonormal matrix of eigenvectors of  $S$ , and  $\Lambda$  is a real and diagonal matrix of corresponding eigenvalues of  $S$ .

To start, let  $\lambda$  be an eigenvalue of  $S$ , and let  $\vec{q}$  be any normalized eigenvector of  $S$  corresponding to eigenvalue  $\lambda$ . Let  $\tilde{Q} \in \mathbb{R}^{n \times (n-1)}$  be a set of orthonormal vectors chosen so that  $Q := \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix} \in \mathbb{R}^{n \times n}$  is an orthonormal matrix.<sup>3</sup> **Show the following equality:**

$$Q^\top S Q = \begin{bmatrix} \lambda & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & S_0 \end{bmatrix} \quad \text{where} \quad S_0 := \tilde{Q}^\top S \tilde{Q}. \quad (3)$$

(HINT: Expand  $Q$  as a block matrix  $\begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix}$  and multiply  $Q^\top S Q = \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix}^\top S \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix}$ .)

(HINT: Since  $Q$  is orthonormal, we have  $Q^\top Q = I_n$ . What does this mean for the values of  $\vec{q}^\top \vec{q}$  and  $\tilde{Q}^\top \tilde{Q}$ ? Use block matrix multiplication on  $Q^\top Q = \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix}^\top \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix}$  again.)

**Solution:** We use block-matrix multiplication:

$$Q^\top S Q = \begin{bmatrix} \vec{q}^\top \\ \tilde{Q}^\top \end{bmatrix} S \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix} \quad (4)$$

$$= \begin{bmatrix} \vec{q}^\top \\ \tilde{Q}^\top \end{bmatrix} \begin{bmatrix} s\vec{q} & s\tilde{Q} \end{bmatrix} \quad (5)$$

$$= \begin{bmatrix} \vec{q}^\top \\ \tilde{Q}^\top \end{bmatrix} \begin{bmatrix} \lambda\vec{q} & s\tilde{Q} \end{bmatrix} \quad (6)$$

$$= \begin{bmatrix} \lambda\vec{q}^\top \vec{q} & \lambda\vec{q}^\top \tilde{Q} \\ \lambda\tilde{Q}^\top \vec{q} & \tilde{Q}^\top s\tilde{Q} \end{bmatrix}. \quad (7)$$

To simplify, we follow the hint, and expand  $Q^\top Q = I_n$ .

$$Q^\top Q = I_n \quad (8)$$

<sup>3</sup>This matrix  $\tilde{Q}$  can be generated via Gram-Schmidt, for example.

$$\begin{bmatrix} \vec{q}^\top \\ \tilde{Q}^\top \end{bmatrix} \begin{bmatrix} \vec{q} & \tilde{Q} \end{bmatrix} = \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & I_{n-1} \end{bmatrix} \quad (9)$$

$$\begin{bmatrix} \vec{q}^\top \vec{q} & \vec{q}^\top \tilde{Q} \\ \tilde{Q}^\top \vec{q} & \tilde{Q}^\top \tilde{Q} \end{bmatrix} = \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & I_{n-1} \end{bmatrix}. \quad (10)$$

Thus we get  $\vec{q}^\top \vec{q} = 1$ ,  $\tilde{Q}^\top \vec{q} = \vec{0}_{n-1}$ ,  $\vec{q}^\top \tilde{Q} = \vec{0}_{n-1}^\top$ , and so we have

$$Q^\top S Q = \begin{bmatrix} \lambda \vec{q}^\top \vec{q} & \vec{q}^\top \tilde{Q} \\ \lambda \tilde{Q}^\top \vec{q} & \tilde{Q}^\top S \tilde{Q} \end{bmatrix} = \begin{bmatrix} \lambda & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & \tilde{Q}^\top S \tilde{Q} \end{bmatrix} \quad (11)$$

(d) **Show that the matrix  $S_0$  is a real symmetric matrix.**

**Solution:** We show that  $S_0^\top = S_0$ .

$$S_0^\top = (\tilde{Q}^\top S \tilde{Q})^\top \quad (12)$$

$$= (\tilde{Q})^\top (S)^\top (\tilde{Q}^\top)^\top \quad (13)$$

$$= \tilde{Q}^\top S^\top \tilde{Q} \quad (14)$$

$$= \tilde{Q}^\top S \tilde{Q} \quad (15)$$

$$= S_0. \quad (16)$$

where the second-to-last equality is because  $S$  is symmetric so  $S^\top = S$ .

It is not necessary to write in the solution, but to show that  $S_0$  is real, note that  $\tilde{Q}$  is real and  $S$  is real, so  $S_0 = \tilde{Q}^\top S \tilde{Q}$  is real as a matrix product of real matrices.

(e) Since  $S_0$  is a real symmetric  $(n-1) \times (n-1)$  matrix, by our inductive assumption,  $S_0$  can be orthonormally diagonalized as  $S_0 = V_0 \Lambda_0 V_0^\top$ , where  $\Lambda_0$  is a real diagonal matrix of eigenvalues of  $S_0$  and  $V_0 \in \mathbb{R}^{(n-1) \times (n-1)}$  is a real orthonormal matrix of corresponding eigenvectors of  $S_0$ .

Define

$$V := Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \quad \text{and} \quad \Lambda := V^\top S V. \quad (17)$$

i. **Show that  $V$  is orthonormal.**

**Solution:** We compute  $V^\top V$ .

$$V^\top V = \left( Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \right)^\top \left( Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \right) \quad (18)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix}^\top Q^\top Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \quad (19)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix}^\top \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \quad (20)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0^\top \end{bmatrix} \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \quad (21)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0^\top V_0 \end{bmatrix} \quad (22)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & I_{n-1} \end{bmatrix} \quad (23)$$

$$= I_n. \quad (24)$$

It is not necessary to write in the solution, but to show that  $V$  is real, note that  $Q$  is real and

$\begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix}$  is real, so  $V = Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix}$  is real as a matrix product of real matrices.

ii. **Show that  $\Lambda$  is diagonal.**

**Solution:** We compute  $\Lambda = V^\top S V$ .

$$\Lambda = V^\top S V \quad (25)$$

$$= \left( Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \right)^\top S \left( Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \right) \quad (26)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix}^\top Q^\top S Q \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \quad (27)$$

$$= \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0^\top \end{bmatrix} \begin{bmatrix} \lambda & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & S_0 \end{bmatrix} \begin{bmatrix} 1 & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0 \end{bmatrix} \quad (28)$$

$$= \begin{bmatrix} \lambda & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & V_0^\top S_0 V_0 \end{bmatrix} \quad (29)$$

$$= \begin{bmatrix} \lambda & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & \Lambda_0 \end{bmatrix}. \quad (30)$$

We already know  $\Lambda_0$  is diagonal so  $\Lambda$  is diagonal.

It is not necessary to write in the solution, but to show that  $\Lambda$  is real, note that  $\lambda$  is real

(shown in part (a)) and  $\Lambda_0$  is real by the induction, so  $\Lambda = \begin{bmatrix} \lambda & \vec{0}_{n-1}^\top \\ \vec{0}_{n-1} & \Lambda_0 \end{bmatrix}$  is real.

iii. **Show that  $S = V \Lambda V^\top$ .**

**Solution:** We have

$$\Lambda = V^\top S V \quad (31)$$

$$\implies V \Lambda = S V \quad (32)$$

$$\implies V \Lambda V^\top = S. \quad (33)$$

(HINT: Use block matrix multiplication again.)

Thus, we have found a real orthonormal  $V$  and real diagonal  $\Lambda$  such that  $S = V \Lambda V^\top = V \Lambda V^{-1}$ . We have seen in a previous homework that if  $A = V \Lambda V^{-1}$ , then  $\Lambda$  are the eigenvalues of  $A$ , and  $V$  are the corresponding eigenvectors. Thus, given  $P_{n-1}$  – the fact that we can orthonormally diagonalize  $(n-1) \times (n-1)$  real symmetric matrices – we have proven  $P_n$  – the fact that we can orthonormally diagonalize  $n \times n$  real symmetric matrices. Thus, we've proved the Spectral Theorem for real symmetric matrices by induction!

## 2. QR System ID Revisited

Recall from your previous homework that, if  $D \in \mathbb{R}^{m \times n}$  where  $m < n$  and  $\text{rank}(D) = m$ , then we can write the QR decomposition of its transpose as

$$D^T = \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} R_1 \\ 0_{(n-m) \times m} \end{bmatrix} \quad (34)$$

The previous homework problem focused on solving a system ID problem, namely solving for  $\vec{p}$  in

$$D\vec{p} = \vec{s} \quad (35)$$

where  $\vec{s} \in \mathbb{R}^m$ . Since this is an underdetermined system, we can have multiplied choices for  $\vec{p}$ . As in the previous homework, we want to find the unique solution that minimizes  $\|\vec{p}\|$ . To do this, we said that we want to set  $Q_2^T \vec{p} = \vec{0}$ . In this problem, we will examine why this minimizes  $\|\vec{p}\|$ .

- (a) **First, show that  $\|\vec{p}\| = \|U\vec{p}\|$  where  $U$  is a matrix with orthonormal columns.** *Warning: a matrix with orthonormal columns is not necessarily an orthonormal matrix. (HINT: Consider squaring both sides of the equation.) (HINT: Recall that  $\|\vec{v}\|^2 = \vec{v}^T \vec{v}$ .) (HINT: It may be useful to note that  $(U^T U)_{ij}$  (the  $(i, j)$ th entry of  $U^T U$ ) is  $\vec{u}_i^T \vec{u}_j$ .)*

**Solution:** Following the hint, we would like to show

$$\|\vec{p}\|^2 = \|U\vec{p}\|^2 \quad (36)$$

Starting with the right hand side, we have

$$\|U\vec{p}\|^2 = (U\vec{p})^T (U\vec{p}) \quad (37)$$

$$= \vec{p}^T U^T U \vec{p} \quad (38)$$

$$= \vec{p}^T \vec{p} \quad (39)$$

$$= \|\vec{p}\|^2 \quad (40)$$

so we have  $\|\vec{p}\|^2 = \|U\vec{p}\|^2$ . Notice that  $(U^T U)_{ij} = 0$  if  $i \neq j$  and 1 if  $i = j$ . Hence,  $U^T U = I$ . Square rooting both sides and noticing that norm is always nonnegative, we have  $\|\vec{p}\| = \|U\vec{p}\|$ .

- (b) **Next, show that  $\|\vec{v} + \vec{u}\|^2 = \|\vec{v}\|^2 + \|\vec{u}\|^2$  for nonzero  $\vec{u}, \vec{v} \in \mathbb{R}^n$  if and only if  $\vec{u}$  and  $\vec{v}$  are orthogonal.**

**Solution:** We have that

$$\|\vec{v} + \vec{u}\|^2 = (\vec{v} + \vec{u})^T (\vec{v} + \vec{u}) \quad (41)$$

$$= \vec{v}^T \vec{v} + \vec{v}^T \vec{u} + \vec{u}^T \vec{v} + \vec{u}^T \vec{u} \quad (42)$$

$$= \|\vec{v}\|^2 + \langle \vec{v}, \vec{u} \rangle + \langle \vec{u}, \vec{v} \rangle + \|\vec{u}\|^2 \quad (43)$$

$$= \|\vec{v}\|^2 + 2 \langle \vec{v}, \vec{u} \rangle + \|\vec{u}\|^2 \quad (44)$$

This expression will be equal to  $\|\vec{v}\|^2 + \|\vec{u}\|^2$  if and only if  $\langle \vec{v}, \vec{u} \rangle = 0$  which is true if and only if  $\vec{u}$  and  $\vec{v}$  are orthogonal.

- (c) Recall from the previous homework that we determined that the value of  $Q_2^T \vec{p}$  does not matter. More explicitly, as long as  $Q_1^T \vec{p} = (R_1^T)^{-1} \vec{s}$ , we can choose  $\vec{p}$  such that  $Q_2^T \vec{p}$  can be any value, and it will not invalidate our solution. **First, show that we can write  $\vec{p}$  as**

$$\vec{p} = Q_1 Q_1^T \vec{p} + Q_2 Q_2^T \vec{p} \quad (45)$$

Then, using this representation as well as the previous two parts, conclude that we should set  $Q_2^\top \vec{p} = \vec{0}$ .

(HINT: For the first part of this problem, there are many ways to approach it, but one way would be to say that  $\vec{p} = \underbrace{QQ^\top}_I \vec{p}$ , write  $Q := \begin{bmatrix} Q_1 & Q_2 \end{bmatrix}$ , and then use block matrix multiplication. Another way to approach this part would be to consider projecting  $\vec{p}$  onto the column space of  $Q_1$  and  $Q_2$  separately (and then show why the summation of these two projections will equal  $\vec{p}$ ).

**Solution:** For the first part of this problem, we can follow the hint to write

$$\vec{p} = QQ^\top \vec{p} \quad (46)$$

$$= \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} Q_1^\top \\ Q_2^\top \end{bmatrix} \vec{p} \quad (47)$$

$$= \begin{bmatrix} Q_1 & Q_2 \end{bmatrix} \begin{bmatrix} Q_1^\top \vec{p} \\ Q_2^\top \vec{p} \end{bmatrix} \quad (48)$$

$$= Q_1 Q_1^\top \vec{p} + Q_2 Q_2^\top \vec{p} \quad (49)$$

We can put norm expressions around this to write

$$\|\vec{p}\| = \left\| Q_1 Q_1^\top \vec{p} + Q_2 Q_2^\top \vec{p} \right\| \quad (50)$$

or, equivalently,

$$\|\vec{p}\|^2 = \left\| Q_1 Q_1^\top \vec{p} + Q_2 Q_2^\top \vec{p} \right\|^2 \quad (51)$$

if we were to square both sides. From the previous part, we have that

$$\left\| Q_1 Q_1^\top \vec{p} + Q_2 Q_2^\top \vec{p} \right\|^2 = \left\| Q_1 Q_1^\top \vec{p} \right\|^2 + \left\| Q_2 Q_2^\top \vec{p} \right\|^2 \quad (52)$$

since any vector in the column space of  $Q_1$  is orthogonal to every vector in the column space of  $Q_2$  (since the columns of  $Q_1$  are orthogonal to the columns of  $Q_2$ ). As such, we can use part (a) again by noticing that the columns in  $Q_1$  are orthonormal as are the columns in  $Q_2$ , so

$$\|\vec{p}\|^2 = \left\| Q_1 Q_1^\top \vec{p} \right\|^2 + \left\| Q_2 Q_2^\top \vec{p} \right\|^2 = \left\| Q_1^\top \vec{p} \right\|^2 + \left\| Q_2^\top \vec{p} \right\|^2 \quad (53)$$

In order to minimize  $\|\vec{p}\|$ , we can equivalently minimize  $\|\vec{p}\|^2$ . Since we can set  $Q_2^\top \vec{p}$  to be any quantity we want, we can set it to  $\vec{0}$  to minimize the expression above.

### 3. SVD System ID

Previously, we saw instances for how to solve system ID problems when  $D \in \mathbb{R}^{m \times n}$  is full rank (separately, for  $m > n$  and  $n > m$ ). Now, let us consider more generally the following problem of estimating  $\vec{p}$  in

$$D\vec{p} = \vec{s} \quad (54)$$

where  $\vec{p} \in \mathbb{R}^n$ ,  $\vec{s} \in \mathbb{R}^m$ , and  $D \in \mathbb{R}^{m \times n}$ . We assume that  $\text{rank}(D) = r < \min(m, n)$ , and we do not make any further assumptions on the relationship between  $m$  and  $n$ . Let's assume that  $D$  has an SVD given by

$$D = U\Sigma V^\top \quad (55)$$

where  $U \in \mathbb{R}^{m \times m}$  and  $V \in \mathbb{R}^{n \times n}$  are orthonormal matrices.  $\Sigma \in \mathbb{R}^{m \times n}$  has the following form:

$$\Sigma = \begin{bmatrix} \Sigma_r & 0_{r \times (n-r)} \\ 0_{(m-r) \times r} & 0_{(m-r) \times (n-r)} \end{bmatrix} \quad (56)$$

where  $\Sigma_r = \begin{bmatrix} \sigma_1 & & & \\ & \sigma_2 & & \\ & & \ddots & \\ & & & \sigma_r \end{bmatrix}$  is a  $r \times r$  diagonal matrix with nonzero elements along its diagonal.

Using this problem setup, we can rewrite our original system ID problem as

$$U\Sigma V^\top \vec{p} = \vec{s} \quad (57)$$

Our goal is to find  $\vec{p}$  with smallest norm that best estimates  $\vec{s}$ .

For notational convenience, denote  $U := \begin{bmatrix} U_r & U_{m-r} \end{bmatrix}$  where  $U_r \in \mathbb{R}^{m \times r}$  is a matrix with the first  $r$  columns of  $U$  and  $U_{m-r} \in \mathbb{R}^{m \times (m-r)}$  is a matrix with the last  $m-r$  columns of  $U$ . Also, denote  $V := \begin{bmatrix} V_r & V_{n-r} \end{bmatrix}$  where  $V_r \in \mathbb{R}^{n \times r}$  is a matrix that has the first  $r$  columns of  $V$ , and  $V_{n-r} \in \mathbb{R}^{n \times (n-r)}$  is a matrix that has the last  $n-r$  columns of  $V$ . From SVD properties, we know that the columns of  $U_r$  form an orthonormal basis for  $\text{Col}(D)$  and that the columns of  $V_{n-r}$  form an orthonormal basis for  $\text{Null}(D)$ .

(a) **Using the fact that  $U$  is orthonormal, show that  $\Sigma V^\top \vec{p} = U^\top \vec{s}$ .**

**Solution:** We have that

$$D\vec{p} = \vec{s} \quad (58)$$

$$U\Sigma V^\top \vec{p} = \vec{s} \quad (59)$$

$$U^\top U\Sigma V^\top \vec{p} = U^\top \vec{s} \quad (60)$$

$$\Sigma V^\top \vec{p} = U^\top \vec{s} \quad (61)$$

(b) **Show that we can write  $\vec{p} = \begin{bmatrix} V_r & V_{n-r} \end{bmatrix} \begin{bmatrix} \vec{\alpha} \\ \vec{\beta} \end{bmatrix}$  for some vectors  $\vec{\alpha}$  and  $\vec{\beta}$  (i.e., find  $\vec{\alpha} \in \mathbb{R}^r$  and  $\vec{\beta} \in \mathbb{R}^{n-r}$ ). Show that changing  $\vec{\beta}$  will not affect the result of  $D\vec{p}$  and that we should set  $\vec{\beta} = \vec{0}$  if we want to minimize  $\|\vec{p}\|$ . This result justifies that we are achieving a  $\vec{p}$  with smallest norm. (HINT:**

For the second part of this question, consider using block matrix multiplication on  $\begin{bmatrix} V_r & V_{n-r} \end{bmatrix} \begin{bmatrix} \vec{\alpha} \\ \vec{\beta} \end{bmatrix}$  (don't substitute for  $\vec{\alpha}$  and  $\vec{\beta}$ ) and leverage the result from the QR decomposition problem on this homework.)

**Solution:** We have that

$$\vec{p} = V \begin{bmatrix} \vec{\alpha} \\ \vec{\beta} \end{bmatrix} \quad (62)$$

$$V^\top \vec{p} = \begin{bmatrix} \vec{\alpha} \\ \vec{\beta} \end{bmatrix} \quad (63)$$

$$\begin{bmatrix} V_r^\top \\ V_{n-r}^\top \end{bmatrix} \vec{p} = \begin{bmatrix} \vec{\alpha} \\ \vec{\beta} \end{bmatrix} \quad (64)$$

$$\begin{bmatrix} V_r^\top \vec{p} \\ V_{n-r}^\top \vec{p} \end{bmatrix} = \begin{bmatrix} \vec{\alpha} \\ \vec{\beta} \end{bmatrix} \quad (65)$$

so  $\vec{\alpha} = V_r^\top \vec{p}$  and  $\vec{\beta} = V_{n-r}^\top \vec{p}$ .

For the second part of this problem, we can follow the hint and write

$$\vec{p} = V_r \vec{\alpha} + V_{n-r} \vec{\beta} \quad (66)$$

Since  $V_{n-r} \vec{\beta}$  is in  $\text{Null}(D)$ , we have that

$$D\vec{p} = DV_r \vec{\alpha} + DV_{n-r} \vec{\beta} = DV_r \vec{\alpha} \quad (67)$$

so the value of  $\vec{\beta}$  does not affect the result of  $D\vec{p}$ . From the result in the QR decomposition problem on this homework, we can set  $\vec{\beta} = \vec{0}$  to minimize the norm of  $\vec{p}$ . Equivalently, we would like to minimize

$$\|\vec{p}\|^2 = \vec{p}^\top \vec{p} \quad (68)$$

$$= (V_r \vec{\alpha} + V_{n-r} \vec{\beta})^\top (V_r \vec{\alpha} + V_{n-r} \vec{\beta}) \quad (69)$$

$$= (\vec{\alpha}^\top V_r^\top + \vec{\beta}^\top V_{n-r}^\top) (V_r \vec{\alpha} + V_{n-r} \vec{\beta}) \quad (70)$$

$$= \vec{\alpha}^\top V_r^\top V_r \vec{\alpha} + \vec{\beta}^\top V_{n-r}^\top V_{n-r} \vec{\beta} + \vec{\alpha}^\top V_r^\top V_{n-r} \vec{\beta} + \vec{\beta}^\top V_{n-r}^\top V_r \vec{\alpha} \quad (71)$$

$$= \vec{\alpha}^\top \vec{\alpha} + \vec{\beta}^\top \vec{\beta} \quad (72)$$

$$= \|\vec{\alpha}\|^2 + \|\vec{\beta}\|^2 \quad (73)$$

which we minimize by setting  $\vec{\beta} = \vec{0}$ . Note that  $V_r^\top V_r = I_r$  and  $V_{n-r}^\top V_{n-r} = I_{n-r}$ . Also,  $V_r^\top V_{n-r} = 0_{r \times (n-r)}$  and  $V_{n-r}^\top V_r = 0_{(n-r) \times r}$  since the columns in  $V_r$  are orthogonal to the columns in  $V_{n-r}$ .

(c) From the previous part, we can rewrite  $\vec{p} = V \begin{bmatrix} \vec{\alpha} \\ \vec{0} \end{bmatrix}$ . This simplifies our system ID problem as follows:

$$\Sigma V^\top V \begin{bmatrix} \vec{\alpha} \\ \vec{0} \end{bmatrix} = U^\top \vec{s} \quad (74)$$

$$\Sigma \begin{bmatrix} \vec{\alpha} \\ \vec{0} \end{bmatrix} = U^\top \vec{s} \quad (75)$$



**Simplify the left hand side of eq. (75) using eq. (56). Rewrite  $U^\top \vec{s}$  as  $\begin{bmatrix} U_r^\top \vec{s} \\ U_{m-r}^\top \vec{s} \end{bmatrix}$  and find an expression for  $\vec{\alpha}$ .** (HINT: Block matrix multiplication will work like normal matrix-vector multiplication here since  $\Sigma_r \in \mathbb{R}^{r \times r}$  and  $\vec{\alpha} \in \mathbb{R}^r$ .)

**Solution:** Following the hint, we have

$$\Sigma \begin{bmatrix} \vec{\alpha} \\ \vec{0} \end{bmatrix} = \begin{bmatrix} \Sigma_r & 0_{r \times (n-r)} \\ 0_{(m-r) \times r} & 0_{(m-r) \times (n-r)} \end{bmatrix} \begin{bmatrix} \vec{\alpha} \\ \vec{0} \end{bmatrix} \quad (76)$$

$$= \begin{bmatrix} \Sigma_r \vec{\alpha} \\ \vec{0} \end{bmatrix} \quad (77)$$

Now, we set this expression equal to  $U^\top \vec{s}$  to obtain

$$\begin{bmatrix} \Sigma_r \vec{\alpha} \\ \vec{0} \end{bmatrix} = \begin{bmatrix} U_r^\top \vec{s} \\ U_{m-r}^\top \vec{s} \end{bmatrix} \quad (78)$$

By looking at the first entry on the left and right hand sides, we have

$$\Sigma_r \vec{\alpha} = U_r^\top \vec{s} \quad (79)$$

$$\vec{\alpha} = \Sigma_r^{-1} U_r^\top \vec{s} \quad (80)$$

where  $\Sigma_r$  is invertible since it is a diagonal matrix with nonzero elements along the diagonal. Explicitly, one may write

$$\Sigma_r^{-1} = \begin{bmatrix} \frac{1}{\sigma_1} & & & \\ & \frac{1}{\sigma_2} & & \\ & & \ddots & \\ & & & \frac{1}{\sigma_r} \end{bmatrix} \quad (81)$$

(d) **Use the previous part to come up with a solution for  $\vec{p}$ .**

**Solution:** From part (b), we have

$$\vec{p} = V \begin{bmatrix} \vec{\alpha} \\ \vec{0} \end{bmatrix} \quad (82)$$

and from the previous part we have

$$\vec{\alpha} = \Sigma_r^{-1} U_r^\top \vec{s} \quad (83)$$

Putting these two together, we have

$$\vec{p} = V \begin{bmatrix} \Sigma_r^{-1} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (84)$$

(e) From the concept of projections, we know that the optimal solution for  $\vec{p}$  satisfies the property that the projection error, namely  $\vec{s} - D\vec{p}$ , is orthogonal to the projection itself, namely  $D\vec{p}$ . Write  $\vec{s} := \begin{bmatrix} U_r & U_{m-r} \end{bmatrix} \begin{bmatrix} \vec{w} \\ \vec{z} \end{bmatrix}$  for some vectors  $\vec{w} \in \mathbb{R}^r$  and  $\vec{z} \in \mathbb{R}^{m-r}$ . **Find  $\vec{w}$  and  $\vec{z}$ . Using this, show that our solution for  $\vec{p}$  is optimal.**

**Solution:** We have that  $\vec{s} = U \begin{bmatrix} \vec{w} \\ \vec{z} \end{bmatrix}$ . Simplifying this,

$$\vec{s} = U \begin{bmatrix} \vec{w} \\ \vec{z} \end{bmatrix} \quad (85)$$

$$U^\top \vec{s} = \begin{bmatrix} \vec{w} \\ \vec{z} \end{bmatrix} \quad (86)$$

$$\begin{bmatrix} U_r^\top \\ U_{m-r}^\top \end{bmatrix} \vec{s} = \begin{bmatrix} \vec{w} \\ \vec{z} \end{bmatrix} \quad (87)$$

$$\begin{bmatrix} U_r^\top \vec{s} \\ U_{m-r}^\top \vec{s} \end{bmatrix} = \begin{bmatrix} \vec{w} \\ \vec{z} \end{bmatrix} \quad (88)$$

so  $\vec{w} = U_r^\top \vec{s}$  and  $\vec{z} = U_{m-r}^\top \vec{s}$ . Now, from the previous part, we have

$$\vec{p} = V \begin{bmatrix} \Sigma_r^{-1} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (89)$$

Plugging this back into the equation  $D\vec{p}$  (where we substitute  $D = U\Sigma V^\top$ ),

$$D\vec{p} = U\Sigma V^\top V \begin{bmatrix} \Sigma_r^{-1} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (90)$$

$$= U\Sigma \begin{bmatrix} \Sigma_r^{-1} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (91)$$

$$= U \begin{bmatrix} \Sigma_r & 0_{r \times (n-r)} \\ 0_{(m-r) \times r} & 0_{(m-r) \times (n-r)} \end{bmatrix} \begin{bmatrix} \Sigma_r^{-1} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (92)$$

$$= U \begin{bmatrix} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (93)$$

Thus, we have that

$$\vec{s} - D\vec{p} = U \begin{bmatrix} U_r^\top \vec{s} \\ U_{m-r}^\top \vec{s} \end{bmatrix} - U \begin{bmatrix} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} = U \begin{bmatrix} \vec{0} \\ U_{m-r}^\top \vec{s} \end{bmatrix} \quad (94)$$

Using this, we have that

$$\langle \vec{s} - D\vec{p}, D\vec{p} \rangle = (\vec{s} - D\vec{p})^\top (D\vec{p}) \quad (95)$$

$$= \left( U \begin{bmatrix} \vec{0} \\ U_{m-r}^\top \vec{s} \end{bmatrix} \right)^\top \left( U \begin{bmatrix} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \right) \quad (96)$$

$$= [\vec{0}^\top \quad \vec{s}^\top U_{m-r}] U^\top U \begin{bmatrix} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (97)$$

$$= [\vec{0}^\top \quad \vec{s}^\top U_{m-r}] \begin{bmatrix} U_r^\top \vec{s} \\ \vec{0} \end{bmatrix} \quad (98)$$

$$= \vec{0}^\top U_r^\top \vec{s} + \vec{s}^\top U_{m-r} \vec{0} \quad (99)$$

$$= 0 \quad (100)$$

so  $\vec{p}$  is optimal.

#### 4. Frobenius Norm

In this problem we will investigate the basic properties of the Frobenius norm.

Similar to how the norm of vector  $\vec{x} \in \mathbb{R}^n$  is defined as  $\|x\| = \sqrt{\sum_{i=1}^n x_i^2}$ , the Frobenius norm of a matrix  $A \in \mathbb{R}^{m \times n}$  is defined as

$$\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |A_{ij}|^2}. \quad (101)$$

$A_{ij}$  is the entry in the  $i^{\text{th}}$  row and the  $j^{\text{th}}$  column. This is basically the norm that comes from treating a matrix like a big vector filled with numbers.

(a) With the above definitions, **show that for a  $2 \times 2$  matrix  $A$ :**

$$\|A\|_F = \sqrt{\text{tr}(A^T A)}. \quad (102)$$

*Note:* The trace of a matrix is the sum of its diagonal entries. For example, let  $A \in \mathbb{R}^{m \times n}$ , then,

$$\text{tr}(A) = \sum_{i=1}^{\min(n,m)} A_{ii} \quad (103)$$

Think about how/whether this expression eq. (102) generalizes to general  $m \times n$  matrices.

**Solution:** This proof is for the general case of  $m \times n$  matrices. You should give yourself full credit if you did this calculation only on the  $2 \times 2$  case.

$$\text{tr}(A^T A) = \sum_{i=1}^n (A^T A)_{ii} \quad (104)$$

$$= \sum_{i=1}^n \left( \sum_{j=1}^m (A^T)_{ij} A_{ji} \right) \quad (105)$$

$$= \sum_{i=1}^n \left( \sum_{j=1}^m A_{ji} A_{ji} \right) \quad (106)$$

$$= \sum_{i=1}^n \sum_{j=1}^m (A_{ji}^2) \quad (107)$$

$$= \|A\|_F^2 \quad (108)$$

In the above solution, step eq. (104) writes out the trace definition, step eq. (105) expands the matrix multiplication on the diagonal indices (i.e. index  $(i, i)$  is the real inner product of row  $i$  and column  $i$ ), step eq. (106) applies the definition of matrix transpose, and the last two steps collect the result into the definition of Frobenius norm.

(b) **Show for any matrix  $A \in \mathbb{R}^{m \times n}$ :**

$$\|A\|_F = \|A^T\|_F \quad (109)$$

A purely written or mathematical solution will be sufficient for this problem.

(*HINT: For the mathematical solution, use the trace interpretation from eq. (101).*)

**Solution:** Written Solution: Intuitively, we know that since the Frobenius norm sums the squares of the elements of a matrix and that transposes change the orientation rather than the contents of the matrix, the norms should be equivalent.

Mathematical Solution: Assume without loss of generality that we sum row by row when calculating the Frobenius norm.

$$\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n |A_{ij}|^2} \quad (110)$$

$$= \sqrt{\sum_{j=1}^n \sum_{i=1}^m |A_{ij}|^2} \quad (111)$$

$$= \sqrt{\sum_{j=1}^n \sum_{i=1}^m |A_{ji}^\top|^2} \quad (112)$$

$$= \|A^\top\|_F \quad (113)$$

The first equality is given. The second equality stems from swapping from summing by each row to summing by each column (equivalent since contents don't change). The third equality stems from the fact that 2D transposed matrices have the indices of their corresponding elements swapped. Finally, since we defined the Frobenius norm as a row-wise sum of the matrix, we know this last equation to be the Frobenius norm of the transposed matrix.

(c) Show that if  $U$  and  $V$  are square orthonormal matrices, then

$$\|UA\|_F = \|AV\|_F = \|A\|_F. \quad (114)$$

(HINT: Use the trace interpretation from part (a) and the equation from part (b).)

**Solution:** The direct path is just to compute using the trace formula:

$$\|UA\|_F = \sqrt{\text{tr}((UA)^\top(UA))} = \sqrt{\text{tr}(A^\top U^\top UA)} = \sqrt{\text{tr}(A^\top A)} = \|A\|_F \quad (115)$$

Another path is to note that the Frobenius norm squared of a matrix is the sum of squared Euclidean norms of the columns of the matrix. Matrix multiplication  $UA$  proceeds to act on each column of  $A$  independently. None of those norms change since  $U$  is orthonormal, and so the Frobenius norm also doesn't change.

To show the second equality, we must first note that  $\|A^\top\|_F = \|A\|_F$ , because we are just summing over the same numbers, just in a different order. Hence:

$$\|AV\|_F = \|(AV)^\top\|_F = \|V^\top A^\top\|_F \quad (116)$$

But the transpose of a square orthonormal matrix is also orthonormal, hence this case reduces to the previous case, implying

$$\|V^\top A^\top\|_F = \|A^\top\|_F = \|A\|_F \quad (117)$$

(d) Use the SVD decomposition to show that  $\|A\|_F = \sqrt{\sum_{i=1}^n \sigma_i^2}$ , where  $\sigma_1, \dots, \sigma_n$  are the singular values of  $A$ .

(HINT: The previous part might be quite useful.)

**Solution:**

$$\|A\|_F = \|\mathbf{U}\Sigma\mathbf{V}^\top\|_F = \|\Sigma\mathbf{V}^\top\|_F = \|\Sigma\|_F \quad (118)$$

$$= \sqrt{\sum_{i=1}^n \sigma_i^2} \quad (119)$$

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